



CENTRE EUROPÉEN DE RECHERCHE ET DE FORMATION AVANCÉE EN **CALCUL SCIENTIFIQUE**

Highly robust iterative, domain decomposition solvers and load balancing aspects in the setup phase

[joint work with A. Klawonn (U Cologne)
and O. Rheinbach (TU Freiberg)]

Martin J. Kühn



EoCoE



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Find $u \in H_0^1(\Omega, \partial\Omega_D)^3$, such that

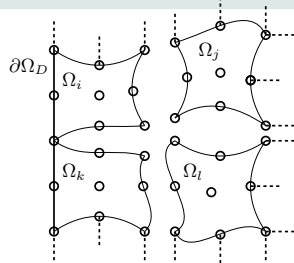
$$\begin{aligned} a(u, v) &= \int_{\Omega} 2\mu \varepsilon(u) : \varepsilon(v) dx + \int_{\Omega} \lambda \operatorname{div}(u) \operatorname{div}(v) dx \\ &= f(v) = \int_{\Omega} f \cdot v dx + \int_{\partial\Omega_N} g \cdot v ds \quad \forall v \in H_0^1(\Omega, \partial\Omega_D)^3 \end{aligned} \quad (1)$$

- ▶ $\Omega \subset \mathbb{R}^3$ bounded polyhedral domain,
- ▶ $\partial\Omega_D \subset \partial\Omega$ a closed subset of nonvanishing measure and $\partial\Omega_N := \partial\Omega \setminus \partial\Omega_D$.
- ▶ $H_0^1(\Omega, \partial\Omega_D)^k := \{v \in H^1(\Omega)^k : v = 0 \text{ on } \partial\Omega_D\}$,
- ▶ λ and μ the Lamé constants depending on Young's modulus $E(x) > 0$, and Poisson's ratio $0 < \nu(x) < \frac{1}{2}$ for all $x \in \Omega$.
- ▶ $f : \Omega \rightarrow \mathbb{R}^3$ volume force
- ▶ $g : \partial\Omega_N \rightarrow \mathbb{R}^3$ surface force

Initial domain decomposition steps:

- ▶ Divide Ω into N nonoverlapping subdomains Ω_i , $i = 1, \dots, N$,
- ▶ assemble local stiffness matrices $K^{(i)}$ and load vectors $f^{(i)}$, $i = 1, \dots, N$.

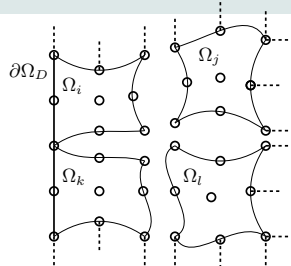
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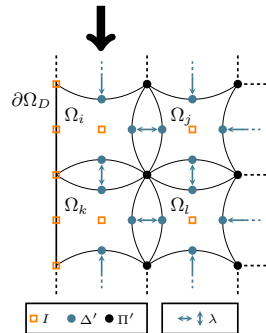


FETI-DP



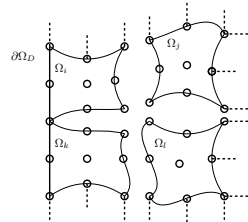
FETI-DP

- ▶ Subdivide the set of variables into inner (I), a priori dual (Δ') and primal (Π') variables (nodes/dofs).
- ▶ Enforce continuity (in each iteration step) at primal variables (nodes/dofs) by subassembly.
- ▶ Enforce continuity (at convergence) at dual variables (nodes/dofs) by Lagrange multipliers λ .



Initial system after domain decomposition:

$$\underbrace{\begin{bmatrix} K^{(1)} & & \\ & \ddots & \\ & & K^{(N)} \end{bmatrix}}_{=:K} \underbrace{\begin{bmatrix} u^{(1)} \\ \vdots \\ u^{(N)} \end{bmatrix}}_{=:u} = \underbrace{\begin{bmatrix} f^{(1)} \\ \vdots \\ f^{(N)} \end{bmatrix}}_{=:f}$$



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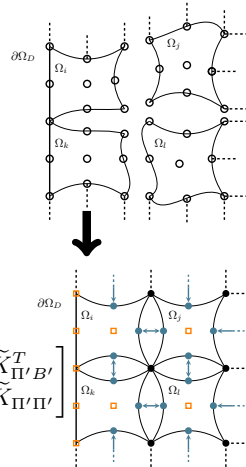


FETI-DP

$$\begin{bmatrix} K_{II}^{(1)} & K_{I\Delta'}^{(1)} & & & \\ K_{\Delta'I}^{(1)} & K_{\Delta'\Delta'}^{(1)} & & & \\ & & \ddots & & \\ & & & K_{II}^{(N)} & K_{I\Delta'}^{(N)} \\ & & & K_{\Delta'I}^{(N)} & K_{\Delta'\Delta'}^{(N)} \\ & & & & & \ddots \\ & & & & & & K_{II}^{(N)} & K_{I\Delta'}^{(N)} \\ & & & & & & K_{\Delta'I}^{(N)} & K_{\Delta'\Delta'}^{(N)} \\ \tilde{K}_{\Pi'I}^{(1)} & \tilde{K}_{\Pi'\Delta'}^{(1)} & \dots & \tilde{K}_{\Pi'I}^{(N)} & \tilde{K}_{\Pi'\Delta'}^{(N)} & \tilde{K}_{\Pi'\Pi'}^{(N)} \end{bmatrix}$$

$$= \begin{bmatrix} K_{B'B'} & \tilde{K}_{\Pi'B'}^T \\ \tilde{K}_{\Pi'B'} & \tilde{K}_{\Pi'\Pi'} \end{bmatrix} \begin{bmatrix} u'_B \\ \tilde{u}'_{\Pi} \\ \lambda \end{bmatrix} = \begin{bmatrix} f'_B \\ \tilde{f}'_{\Pi'} \\ 0 \end{bmatrix}$$

and the introduction of LM λ yields the system:



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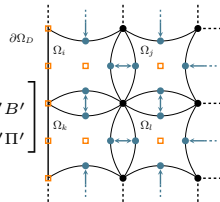
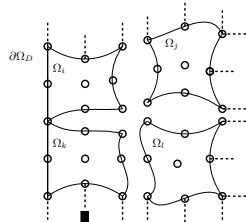
FETI-DP



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$$\begin{bmatrix} \tilde{K}_{\Pi'I}^{(1)T} \\ \tilde{K}_{\Pi'\Delta'}^{(1)T} \\ \vdots \\ \tilde{K}_{\Pi'I}^{(N)T} \\ \tilde{K}_{\Pi'\Delta'}^{(N)T} \\ \tilde{K}_{\Pi'\Pi'}^{(N)T} \end{bmatrix} =: \begin{bmatrix} K_{B'B'} & \tilde{K}_{\Pi'B'}^T \\ \tilde{K}_{\Pi'B'} & \tilde{K}_{\Pi'\Pi'} \end{bmatrix}$$



and the introduction of LM λ yields the system:

$$\begin{bmatrix} \tilde{K} & B^T \\ B & O \end{bmatrix} \begin{bmatrix} \tilde{u} \\ \lambda \end{bmatrix} = \begin{bmatrix} \tilde{f} \\ 0 \end{bmatrix}$$

Unpreconditioned system: after reducing to the Lagrange multipliers:

$$F := B\tilde{K}^{-1}B^T\lambda = B\tilde{K}^{-1}\tilde{f} =: d$$

$$F = \underbrace{B_{B'}K_{B'B'}^{-1}B_{B'}^T}_{\text{local solvers}} + \underbrace{B_{B'}K_{B'B'}^{-1}\tilde{K}_{B'\Pi'}\tilde{S}_{\Pi'\Pi'}^{-1}\tilde{K}_{\Pi'B'}K_{B'B'}^{-1}B_{B'}^T}_{\text{coarse problem; coupled!}}.$$

Dirichlet-Preconditioner: $M_D^{-1} := B_D S B_D^T$ (Sum of local operators!)

1. S : Schur complement of K after elimination of the interior variables
2. B_D : appropriately scaled jump operator on Δ' ; scaling depends on coefficients

Standard FETI-DP is PCG solving

$$M_D^{-1}F\lambda = M_D^{-1}d$$

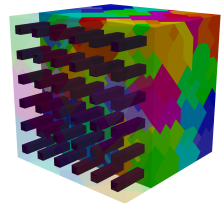
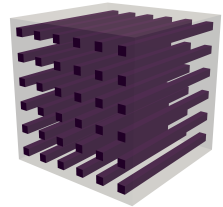
For more details, see, e.g., Farhat et al. (2001), Farhat et al. (2000), Mandel/Tezaur (2001), Klawonn et al. (2002), Klawonn/Widlund (2006), Klawonn/Rheinbach (2007) and the references therein.



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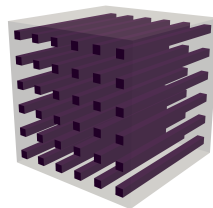


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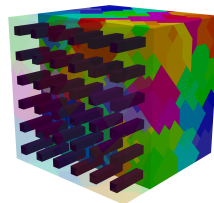
Standard FETI-DP^{*1}

N	$ \Pi' $	cond	iter	time	$\ r^{(i)}\ $
216	9,828	2.09e+6	>5000	480s	5.61e-05 ^{*2}

Table: Compressible linear elasticity of a matrix material with $E_1=1$ surrounding beams with $E_2=1e+6$. $1.02e+6$ degrees of freedom. \mathcal{P}_2 elements.



- ▶ ^{*1}: FETI-DP w/ Dirichlet precondition., vertex + edge average coarse space.
- ▶ ^{*2}: relative reduction by a factor of $1e-4$ after 5000 iterations.
- ▶ N : number of subdomains and cores
- ▶ $|\Pi'|$: size of the corresponding nonadaptive (a priori) coarse space.
- ▶ cond: condition number of the preconditioned FETI-DP operator.
- ▶ iter: number of iterations of the PCG algorithm.
- ▶ $\|r^{(i)}\|$: true residual norm
- ▶ time: total runtime (in seconds)



► Solve (local) eigenvalue problems for a priori tolerances (nonexhaustive)

Our approach Klawonn/Kühn/Rheinbach (2016,2017,2018,2019)

based on Mandel/Sousedík (2007), Sousedík (2008), Klawonn/Radtke/Rheinbach (2016).

Related works: Bjørstad/Koster/Krzyzanowski (2001), Bjørstad/Krzyzanowski (2002), Sousedík (2010), Galvis/Efendiev (2010), Nataf/Xiang/Dolean (2010), Nataf/Xiang/Dolean/Spillane (2011), Dolean/Nataf/Scheichl/Spillane (2012), Šístek/Mandel/Sousedík (2012), Sousedík/Šístek/Mandel (2013), Spillane/Rixen (2013), Dohrmann/Pechstein (2013,2017), Jolivet/Hecht/Nataf/Prud'homme (2014), Spillane (2014,2016), Klawonn/Radtke/Rheinbach (2014,2015), Kim/Chung (2015), Gosselet/Rixen/Roux/Spillane (2015), Radtke (2015), Zampini (2016), Gander/Loneland/Rahman (TR2015), Beirão da Veiga/Pavarino/Scacchi/Widlund/Zampini (2017), Calvo/Widlund (2016), Oh/Widlund/Zampini/Dohrmann (2017), Haferssas/Jolivet/Nataf (2017), Kim/Chung/Wang (2017), Heinlein/Klawonn/Knepper/Rheinbach (2018), Bovet/Parret-Fréaud/Spillane/Gosselet (2017), Eikeland/Marcinkowski/Rahman (TR2016), Barrenechea/Bosy/Dolean (2018), Marcinkowski/Rahman (2018), Agullo/Giraud/Poirel (2019), Al Daas/Grigori (2019), ...

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► Enforce constraints based on computed eigenvectors:

► Implementation I: Optional Lagrange Multipliers or Saddle Point Problems

(Farhat/Lesoinne/Pierson (2000), Mandel/Dohrmann/Tezaur (2004), Mandel/Sousedík (2007), ...)

► Implementation II: Deflation and Balancing (FETI-DP only)

(Nicolaidis (1987), Dostál (1988), Nabben/Vuik (2006), Domorádová(Jarošová)/Dostál (2007), Jarošová/Klawonn/Rheinbach (2012), Klawonn/Rheinbach (2012), ...)

► Implementation III: (Generalized) Transformation-of-Basis approach

(Klawonn/Widlund (2001,2006), Klawonn/Widlund/Dryja (2002), Li/Widlund (2005), Klawonn/Rheinbach (2006, 2007), ..., Klawonn/Kühn/Rheinbach (TR2017, ETNA 2018))



Define $P_D := B_D^T B$ and \tilde{S} : Schur complement on the interface, coupled in some primal variables.

- Condition number bound for standard FETI-DP with coarse space Π' :

$$|P_D w|_{\tilde{S}} \leq C |w|_{\tilde{S}} \quad \forall w : w \text{ cont. in } \Pi' \quad \Rightarrow \quad \kappa(M_D^{-1} F) \leq C.$$

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$$|P_D w|_{\tilde{S}} \geq \text{TOL} |w|_{\tilde{S}}$$

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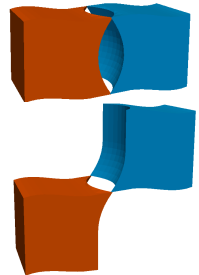
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- Attention: P_D and \tilde{S} are global operators!



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- Adaptive FETI-DP approach based on the P_D estimate:
 \mathcal{Z} (face or edge of $\{\Omega_i, \Omega_s\}$): $P_{D,\mathcal{Z}}$ and \tilde{S}_{is} : localized P_D and \tilde{S} ;
TOL: a priori tolerance. Use w_{is}^l , $l = 1, 2, \dots$ with

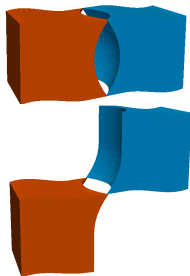
$$|P_{D,\mathcal{Z}} w_{is}^l|_{\tilde{S}_{is}} \geq \text{TOL} |w_{is}^l|_{\tilde{S}_{is}}$$

to set up a second coarse space Π

→ use of a transformation:

continuity in Π means

orthogonality to $\text{span}\{w_{is}^l : l = 1, 2, \dots\}$!



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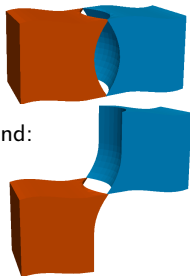
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- From local $P_{D,\mathcal{Z}}$ to global P_D to condition number bound:

For adaptive FETI-DP with coarse space $\Pi' \cup \Pi$:

$$|P_D w|_{\tilde{S}} \leq \text{TOL} \cdot G |w|_{\tilde{S}} \quad \forall w : w \text{ cont. in } \Pi' \cup \Pi$$

$$\Rightarrow \kappa(M_D^{-1} F) \leq \text{TOL} \cdot G.$$





- ▶ local eigenvector constraints \rightsquigarrow global condition number bound
- ▶ depending on **user-defined TOL**, in practice
(and **geometrical constants**, in theory)

Theorem

All vertices primal.

- ▶ $N_{\mathcal{F}}$: *maximum number of faces of a subdomain*
- ▶ $N_{\mathcal{E}}$: *maximum number of edges of a subdomain*
- ▶ $M_{\mathcal{E}}$: *maximum multiplicity of an edge*
- ▶ TOL: *user-defined tolerance for solving the local eigenproblems*

FETI-DP with local adaptive constraints enforced by generalized transformation-of-basis approach, satisfies

$$\kappa(\widehat{M}_T^{-1} \widehat{F}) \leq 4 \max\{N_{\mathcal{F}}, N_{\mathcal{E}} M_{\mathcal{E}}\}^2 \text{TOL}.$$

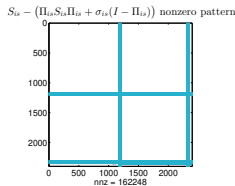
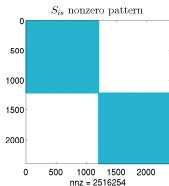
- ▶ e.g., Ω_i and Ω_s share a face \mathcal{Z}
- ▶ two projections Π_{is} and $\bar{\Pi}_{is}$ (**matrix-free**) to remove rigid body modes
- ▶ For $\mu_{is}^l \geq \text{TOL}$, we solve the generalized eigenvalue problem

$$\bar{\Pi}_{is} \Pi_{is} P_{D,\mathcal{Z}}^T \begin{bmatrix} S_i & 0 \\ 0 & S_s \end{bmatrix} P_{D,\mathcal{Z}} \Pi_{is} \bar{\Pi}_{is} w_{is}^l$$

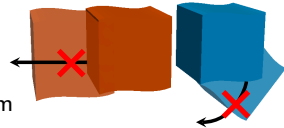
$$= \mu_{is}^l (\bar{\Pi}_{is} (\Pi_{is} \begin{bmatrix} S_i & 0 \\ 0 & S_s \end{bmatrix} \Pi_{is} + \sigma(I - \Pi_{is})) \bar{\Pi}_{is} + \sigma(I - \bar{\Pi}_{is})) w_{is}^l.$$

either on rank i or rank s .

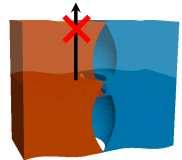
~> **computational overhead and load balance?**



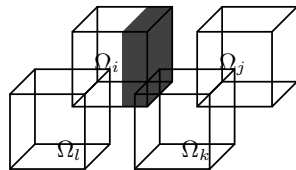
Π_{is} :



$\bar{\Pi}_{is}$:

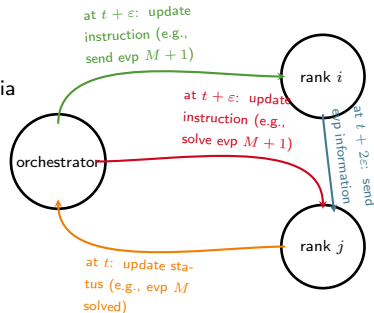


- ▶ C/C++, PETSc 3.8.0, and SLEPc 3.8.0
- ▶ rough solution of the eigenvalue problems
- ▶ only a subset of eigenvalue problems is solved
- ▶ for eigenvalue problem setup: **nonblocking** and **point-to-point**, plain MPI (MPI_IRecv and MPI_Isend) communication



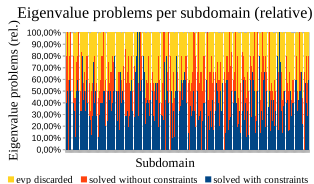
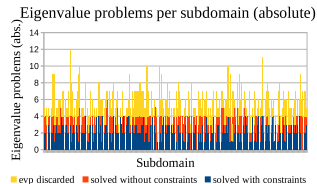
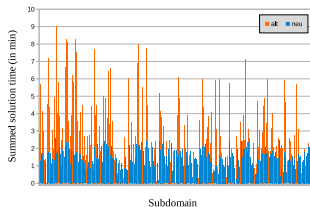
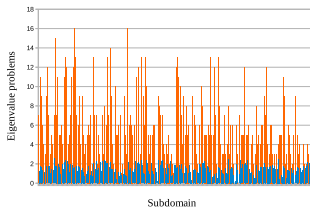
- ▶ one **orchestrating rank**
 - ▶ **collecting** and **distributing** the eigenvalue problems (i.e., index information) **a priori** (via MPI_Scatterv and MPI_Bcast)
 - ▶ **supervising** the solution process and **redistributing (in runtime!)** the eigenvalue problems (i.e., index information) via **nonblocking** and **point-to-point** communication

→ **enhanced load balancing!**



Domain decomposition with adaptive coarse spaces

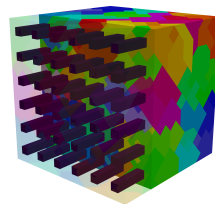
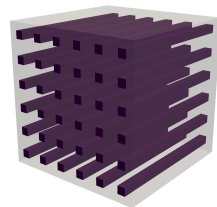
Discarded evp and load balance for adaptive FETI-DP





Domain decomposition with adaptive coarse spaces

Standard vs. adaptive FETI-DP



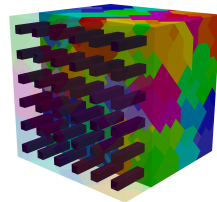
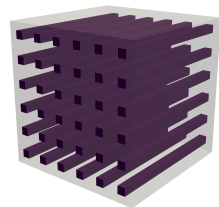
Standard FETI-DP*¹

$ \Pi' $	$ \Pi $	cond	iter	time	$\ r^{(i)}\ $
9,828	-	2.09e+6	>5000	480s	5.61e-05* ²

Adaptive FETI-DP*³

$ \Pi' $	$ \Pi $	cond	iter	time	$\ r^{(i)}\ $
9,483	4,129	54.85	61	143s	5.35e-09* ⁴

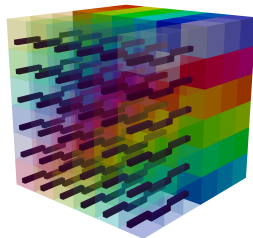
Table: Compressible linear elasticity of a matrix material with $E_1=1$ surrounding beams with $E_2=1e+6$. \mathcal{P}_2 elements. 216 subdomains and cores, $1.02e+6$ degrees of freedom



- ▶ *¹: FETI-DP w/ Dirichlet preconditioning, vertex + edge average coarse space.
- ▶ *²: relative reduction by a factor of $1e-4$ after 5000 iterations.
- ▶ *³: Adaptive FETI-DP (Klawonn/Kühn/Rheinbach (2016-2019)) with single vector KrylovSchur eigensolver
- ▶ *⁴: relative reduction by a factor of $1e-8$ after 61 iterations.
- ▶ $|\Pi'|$: size of the corresponding nonadaptive (a priori) coarse space.
- ▶ cond: condition number of the preconditioned FETI-DP operator.
- ▶ iter: number of iterations of the PCG algorithm.
- ▶ $\|r^{(i)}\|$: true residual norm
- ▶ time: total runtime (in seconds)

Composite material:

- ▶ regular decomposition of the unit cube:
 N subdomains
- ▶ zero Dirichlet boundary conditions on the entire boundary
- ▶ homogeneous $\nu = 0.3$
- ▶ inhomogeneous $E \in \{1, 1e + 6\}$ in form of $N^{2/3}$ chopped beams (as illustrated)



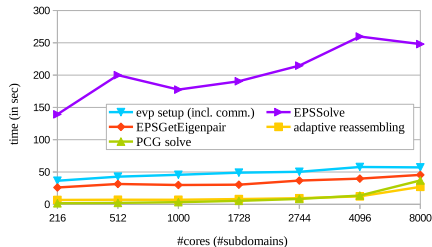
Example: $N = 216$
subdomains in different colors
high coefficients $1e + 6$ in dark purple



Domain decomposition with adaptive coarse spaces

Weak scaling of adaptive FETI-DP

Weak scaling details for regular decompositions

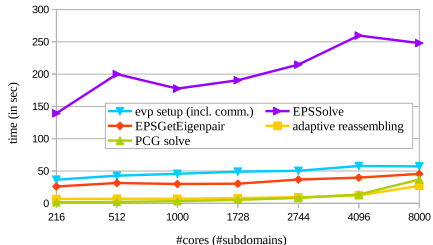


N (#cores-1)	cond.	iter	$ \Pi' $	$ \Pi $	nnz (coarse)	d.o.f.	time	eff.
216	14.02	35	375	1677	2.04e+5	1.17e+6	209s	100%
512	20.12	39	1029	4175	5.43e+5	2.74e+6	274s	76%
1000	24.60	43	2187	8551	1.18e+6	5.31e+6	266s	78%
1728	27.91	47	3993	15512	2.25e+6	9.15e+6	283s	74%
2744	30.22	50	6591	25545	3.82e+6	1.45e+7	320s	65%
4096	32.90	52	10125	39173	5.98e+6	2.16e+7	381s	55%
8000	39.39	59	20577	79097	1.24e+7	4.20e+7	409s	51%

Table: Compressible linear elasticity of a matrix material with $E_1=1$ surrounding chopped beams and $E_2=1e+6$. \mathcal{P}_2 elements. Block size 10 for KrylovSchur eigensolver.

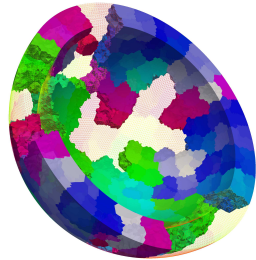
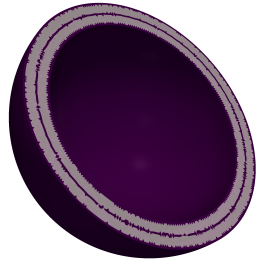
- ▶ N (#cores-1): number of subdomains and cores-1
- ▶ cond: condition number of the preconditioned FETI-DPo perator.
- ▶ iter: number of iterations of the PCG algorithm.
- ▶ nnz (coarse): nonzeros in the coarse matrix
- ▶ $|\Pi'|$: size of the corresponding nonadaptive (a priori) coarse space
- ▶ $|\Pi|$: size of the corresponding adaptive (a posteriori) coarse space
- ▶ d.o.f.: total number of degrees of freedom
- ▶ time: total runtime (in seconds)
- ▶ eff: efficiency of the algorithm

Weak scaling details for regular decompositions



Composite material:

- ▶ hemisphere
- ▶ unstructured mesh
- ▶ zero Dirichlet boundary conditions on the upper part
- ▶ zero Neumann boundary conditions elsewhere
- ▶ homogeneous $\nu = 0.3$
- ▶ inhomogeneous $E \in \{1, 1e+6\}$ in form of layers (as illustrated)
- ▶ 2.6 million degrees of freedom

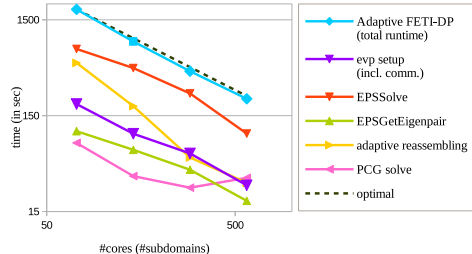




Domain decomposition with adaptive coarse spaces

Strong scaling of adaptive FETI-DP

Strong scaling behavior of adaptive FETI-DP and essential code parts

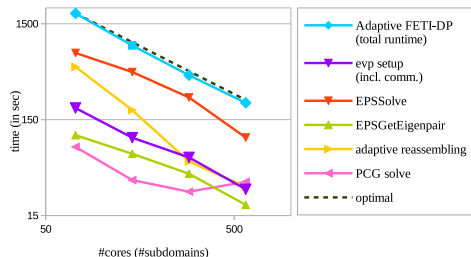


N (#cores-1)	cond.	iter	$ \Pi' $	$ \Pi $	nnz (coarse)	time	eff.
72	109.21	89	1248	4733	$2.97\text{e}+6$	1925s	100%
144	80.62	80	3003	9392	$6.46\text{e}+6$	890s	108%
288	77.20	81	9843	13704	$1.33\text{e}+7$	436s	110%
576	72.02	74	24033	16251	$2.17\text{e}+7$	224s	107%

Table: Compressible linear elasticity on a hemisphere; a soft material with $E_1=1$ in layers with a stiff material with $E_2=1\text{e}+6$. \mathcal{P}_2 elements. 2.6 million degrees of freedom. Single vector KrylovSchur eigensolver.

- N (#cores-1): number of subdomains and cores-1
- cond: condition number of the preconditioned FETI-DP operator.
- iter: number of iterations of the PCG algorithm.
- nnz (coarse): nonzeros in the coarse matrix
- $|\Pi'|$: size of the corresponding nonadaptive (a priori) coarse space
- $|\Pi|$: size of the corresponding adaptive (a posteriori) coarse space
- time: total runtime (in seconds)
- eff: efficiency of the algorithm

Strong scaling behavior of adaptive FETI-DP and essential code parts



ν	cond.	iter	$ \Pi' \cup \Pi $
0.45	6.52	27	4085
0.499	7.34	30	4736
0.49999	6.81	28	4909
0.4999999	6.81	28	4913
0.499999999	6.81	28	4913

Table: Almost incompressible linear elasticity of a homogeneous cubic material with $E=1$ and ν as given, decomposed into 64 subdomains. $\mathcal{Q}_2\mathcal{P}_0$ elements.

- ▶ ν : Poisson ratio
- ▶ cond: condition number of the preconditioned FETI-DP operator.
- ▶ iter: number of iterations of the PCG algorithm.
- ▶ $|\Pi' \cup \Pi|$: size of the corresponding coarse space



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The funding from the European Union's Horizon 2020 research and innovation programme under grant agreement no. 824158 is also greatly acknowledged.



Thank you for your kind attention!

- ▶ Parallel results:

A. Klawonn, M. J. Kühn, O. Rheinbach

“Parallel adaptive FETI-DP using
lightweight asynchronous dynamic load balancing”

Technical Report: CDS-TR-2019-7

- ▶ Theoretical details:

A. Klawonn, M. Kühn, O. Rheinbach

“Adaptive Coarse Spaces for FETI-DP in Three Dimensions”
SIAM J. Sci. Comput., Vol. 38(5), pp. A2880–A2911.